

# Integrated Safety Incident Forecasting and Analysis

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## Project: Objective: Develop Principled Algorithmic Decision Procedures for Emergency Response

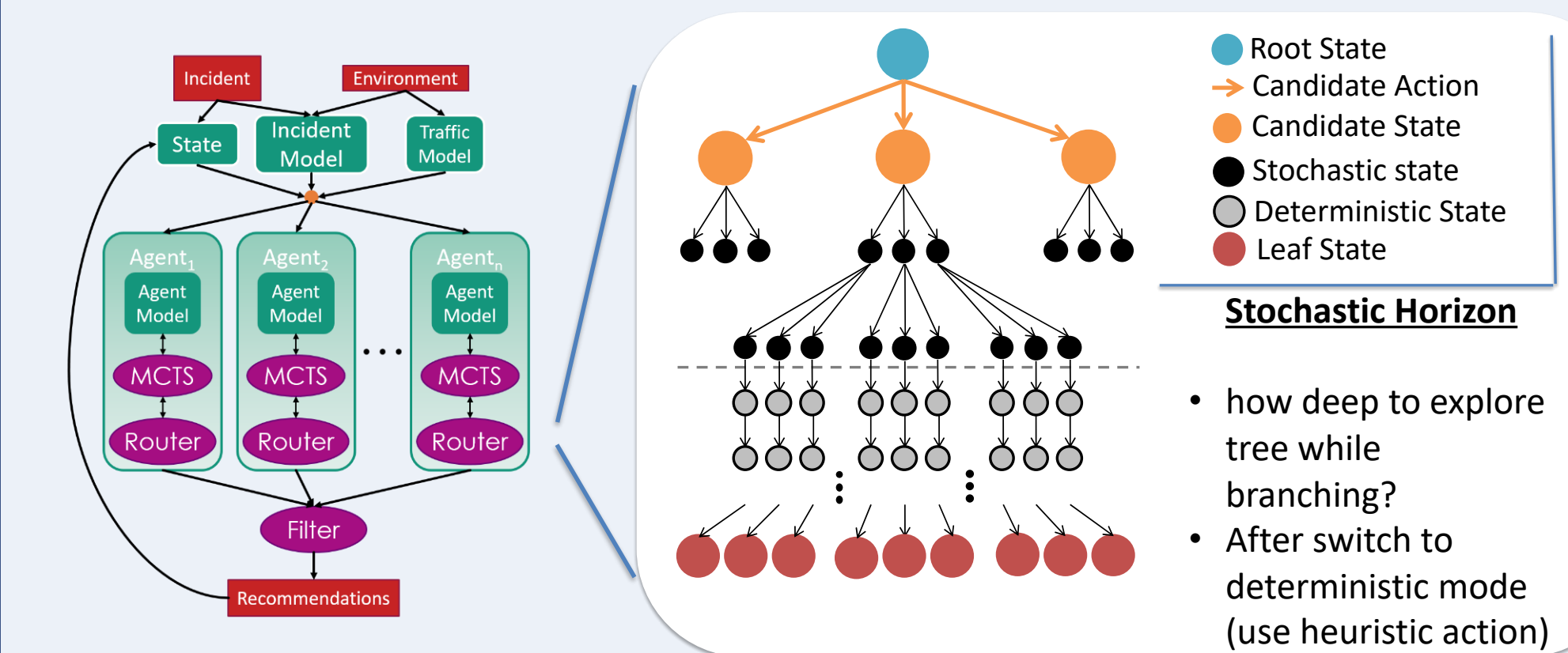
- There are limited emergency responder resources.
- How to assign resources to incidents while reducing average response time
- Decision must be made quickly.



- The planning process should occur before incidents. It is difficult to justify sending anyone but the closest responder at the time of an incident's occurrence.
- Optimizing over responder distribution and response as a multi-objective optimization problem is typically computationally infeasible.
- Example: let the number of responders  $r=20$ , and the number of possible depot locations be  $d=30$ . Possible actions for dispatching is the number of responders  $\rightarrow 20$
- Possible actions for rebalancing is  $P(d, r) = 30!/10! = 7.31 \times 10^{25}$ .

## Our Approach: Partially Decentralized Decision Process

- We focus on three problems (a) designing an accurate incident prediction model; (b) design approach for rebalancing the responders pre-incident and (c) designing an emergency response system that is equipped to deal with scenarios that require decentralized planning with very limited communication.



**Reward function:** The primary metric to consider is the response time for each incident. Secondly, the movement of responders needs to be controlled

$$r_s^d = \begin{cases} r_{s-1} - \alpha^{t_s}(t_s^d), & \text{if responding to an incident} \\ r_{s-1} - \alpha^{t_s} \psi \frac{\sum_{i \in \mathcal{A}} (d_i^d)}{|\mathcal{A}|}, & \text{if balancing at } s \end{cases}$$

## Online Incident Prediction

- Features:** Weather, time, previous incidents, neighboring incidents
- Needs to react to dynamic incident occurrence
- Streaming survival analysis:**

$$L = \prod_i h(\log(t_i) - \bar{\beta}W)$$

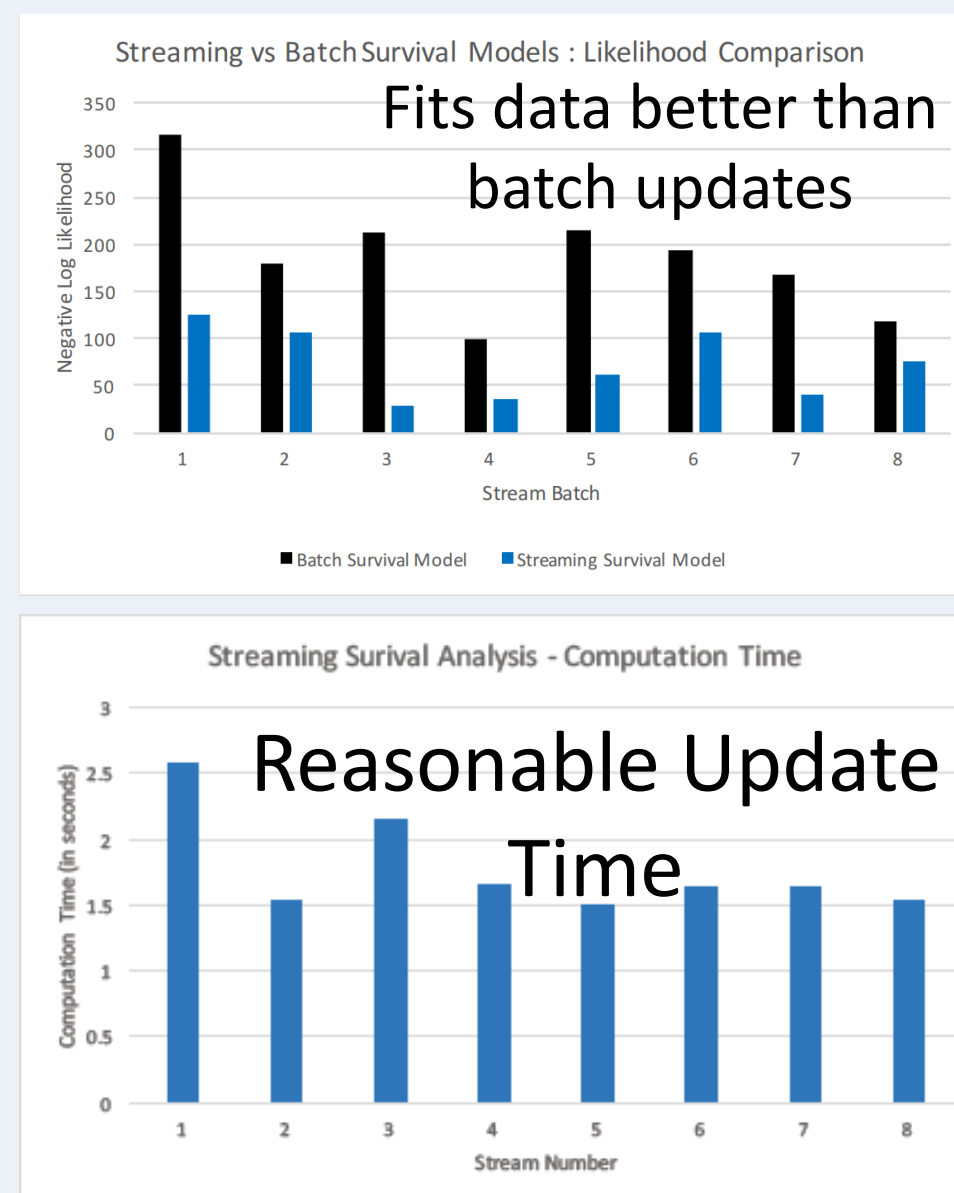
Probabilistic Model for Incident Prediction

$$\beta^{p+1} = \beta^p + \alpha \nabla L(\beta^p, D')$$

Online Update of Coefficients

$$\frac{\partial L}{\partial \beta_j} = \sum_{i=1}^k -w_{ij} + w_{ij} \{e^{(\log \tau_i - \beta^* w_i)}\}$$

Gradient Calculation



## Preemptive Rate Based Rebalancing

- We use a multi-class queue model to enable the responders to anticipate the action of other responders.
- Multiple cells serviced by each depot and vice versa
- Must split request rate for cells between depots
- Since depots closer to a cell are more likely to service it, rates are split such that they are inversely proportional to the distance

$$\sum_{d \in D} v_g^d = v_g$$

$$\text{dist}(d_1, g) v_g^{d_1} = \text{dist}(d_2, g) v_g^{d_2} \quad \forall d, d_2 \in D$$

$$\pi = \sum_{d \in D} \sum_{g \in G} \text{responseTime}(c, v_g^d, \mu) + \text{travelTime}(d, g)$$

Where  $c$  is number of responders at depot,  $v$  is split incident rate, and  $\mu$  is the service rate.  $\text{responseTime}(c, v_g^d, \mu)$  is  $M/M/c$  queue response time,  $\text{travelTime}(d, g)$  is the time to travel from depot  $d$  to the grid in question  $g$

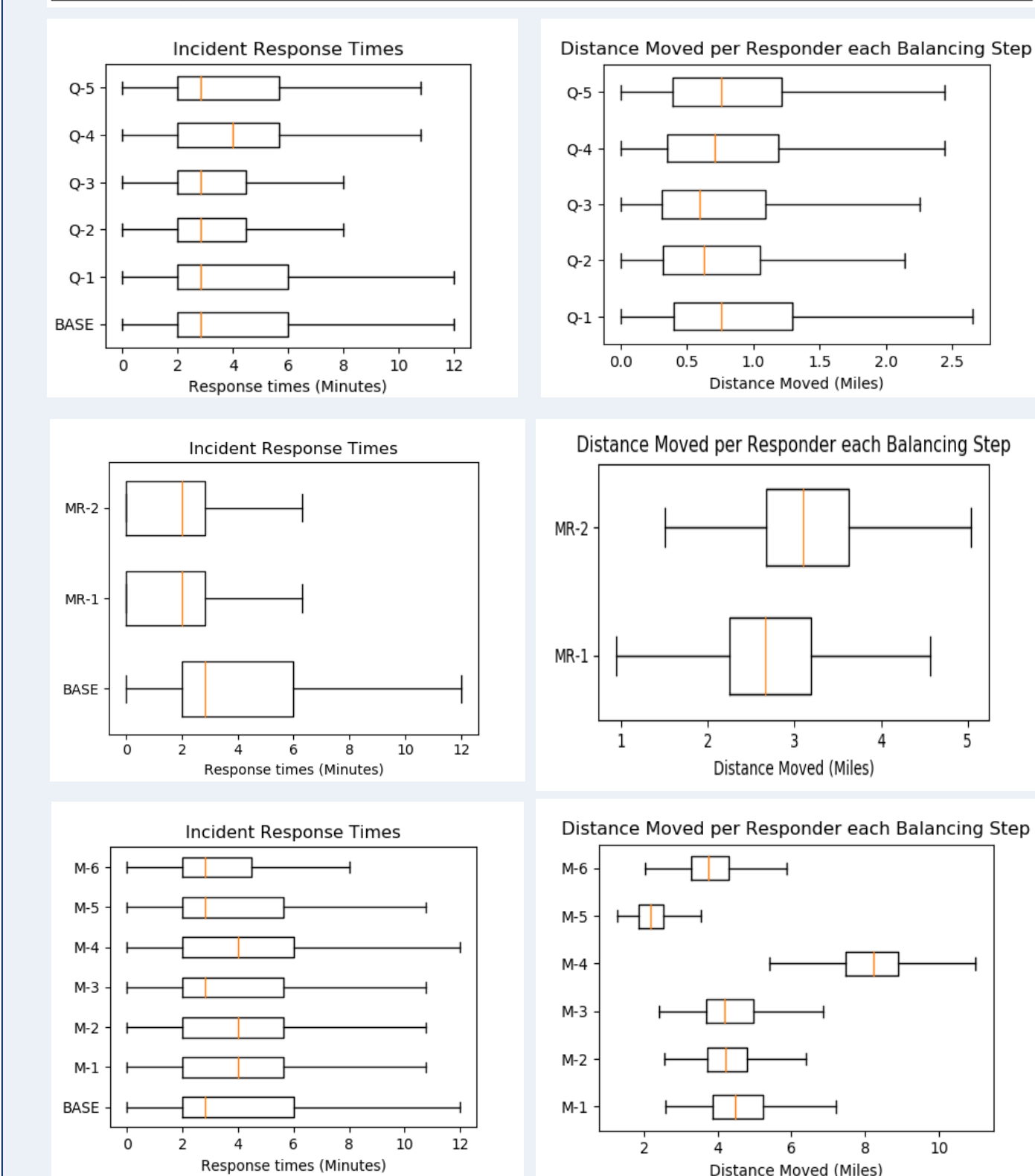
- To score a particular assignment of responders to depots, all response times (computed from multi class queue formulation) are summed using the split rates.
- To determine the best placement, an iterative greedy search is used to select the best depots one at a time using the above score

## Integrated Dashboard



## Results

| Identifier | Description  | Hyper-Parameter Choices  |
|------------|--|--|
| BASE       | Greedy Baseline Without Rebalancing  | N/A  |
| Q-1        | Queue Based Rebalancing Policy with RoI of 1   | RoI = 1  |
| Q-2        | Queue Based Rebalancing Policy with RoI of 2   | RoI = 2  |
| Q-3        | Queue Based Rebalancing Policy with RoI of 3   | RoI = 3  |
| Q-4        | Queue Based Rebalancing Policy with RoI of 4   | RoI = 4  |
| Q-5        | Queue Based Rebalancing Policy with RoI of 5   | RoI = 5  |
| MR-1       | MMCTS - using an oracle for future incidents and a Static Agent Policy   | Same as MMCTS Baseline M-1   |
| MR-2       | MMCTS - using an oracle for future incidents and a Queue Rebalancing Policy  | Same as MMCTS Baseline M-1   |
| M-1        | MMCTS - Baseline. The foundation for the parameter search. Each parameter varies independently while other parameters retain these values. (All M-* experiments use generated incident chains and a Static Agent Policy) | MCTS Iteration Limit = 250<br>Lookahead Horizon = 120 min<br>Reward Distance Weight $\psi = 10$<br>Reward Discount Factor = 0.99995<br>Rebalance Period = 60 min |
| M-2        | MMCTS - Iteration Limit of 100   | MCTS Iteration Limit = 100*  |
| M-3        | MMCTS - Iteration Limit of 500   | MCTS Iteration Limit = 500*  |
| M-4        | MMCTS - Reward Distance Weight $\psi$ of 0   | Reward Distance Weight $\psi = 0^*$  |
| M-5        | MMCTS - Reward Distance Weight $\psi$ of 100   | Reward Distance Weight $\psi = 100^*$  |
| M-6        | MMCTS - Rebalance Period of 30 minutes; Lookahead Horizon of 30 minutes  | Lookahead Horizon = 30 min*<br>Rebalance Period = 30min*   |



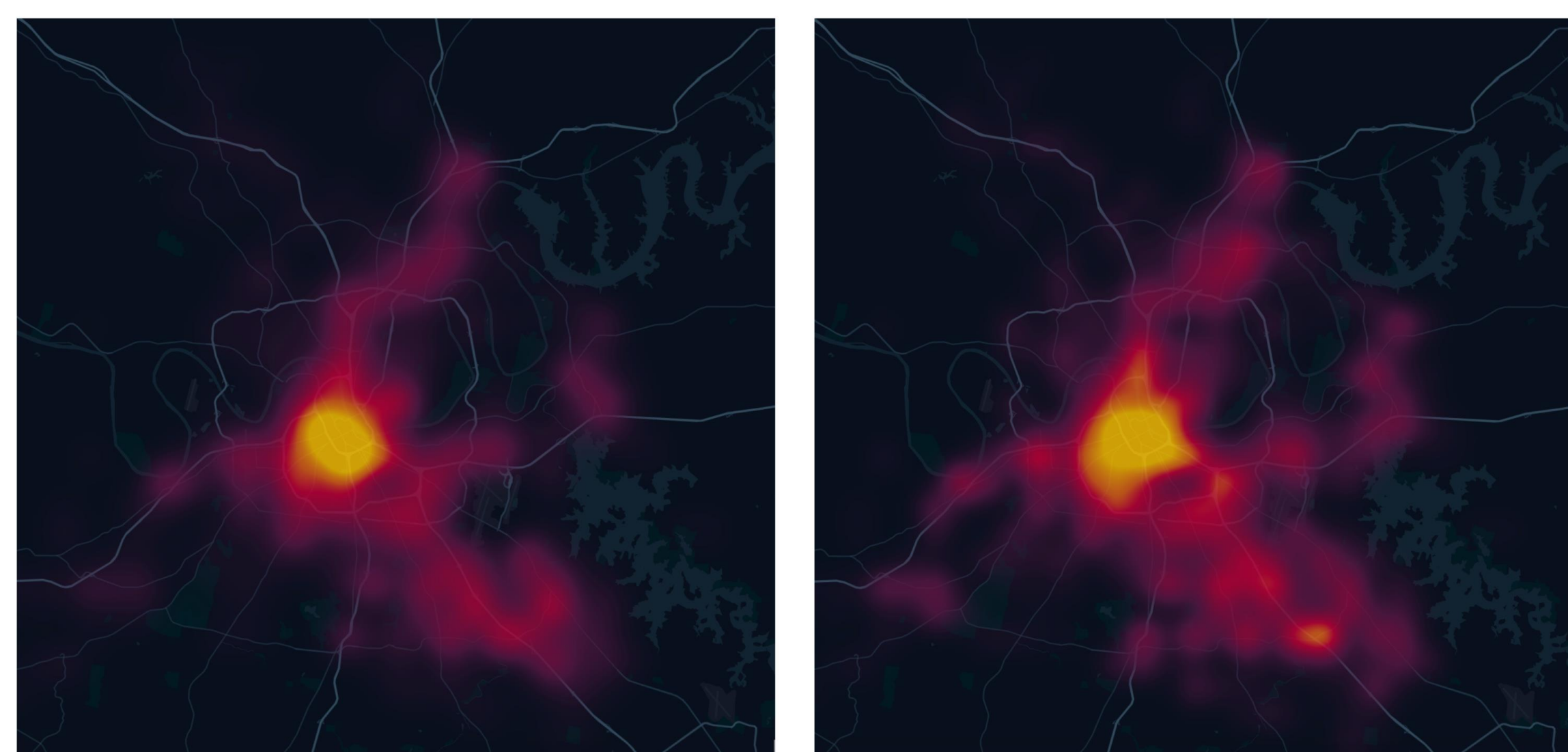
**MMCTS performs better than greedy baseline with most parameters**  
**Oracle solutions show the potential upside. It requires an even better incident forecasting model.**

- Data: Nashville, TN incident data
- Training for predictive model: 1-1-2018 to 1-1-2019
- Testing: 1-1-2019 to 2-1-2019
- Utilized Regions of Interest (RoI) for queue model: Only depots within a cell's RoI are considered when splitting its rate
- Encourages even responder distribution
- Reduces computation time
- Explored several parameters for MMCTS, particularly the distance reward weight and iteration limit for MCTS
- Compared to the incumbent policy of greedy dispatch without rebalancing as a baseline
- An Oracle refers to an incident predictor with perfect knowledge about future incidents (best case scenario for MCTS)

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<https://github.com/scope-lab-vu/DataDrivenEMSDispatch>



Comparison of (1) incidents predicted by model (left), and (2) real incident distribution (right) over January 2019